

Introduction and Assessment of iNewton for the Engaged Learning of Engineering Dynamics

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Introduction

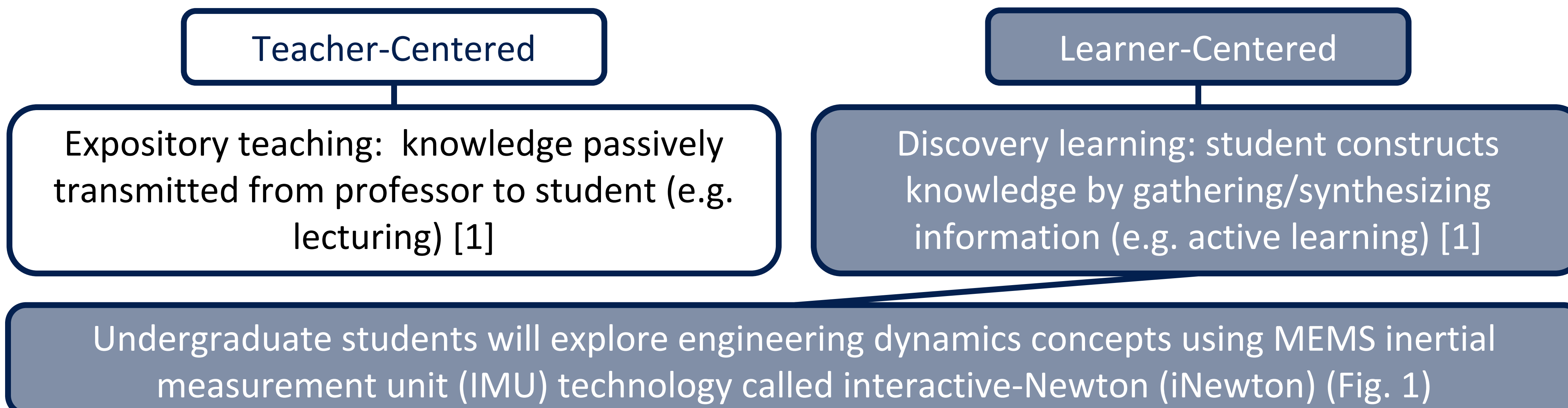


Table 1: Project design to systematically scale up iNewton learning intervention in an otherwise traditional (lecture-only) dynamics course (MECHENG 240).

Level	Intervention (and progress to date)	Description
1	Instructor-Created, Instructor-Led (completed)	Instructors demonstrate two experiments with iNewtons in class for students
2	Instructor-Created, Student-Led (in progress)	Students conduct two pre-defined experiments with iNewtons outside class
3	Student-Created, Student-Led (under development)	Students propose and conduct experiments of their own imagining (with instructor feedback) with iNewtons outside class

Hypothesis: iNewton will positively affect: 1) conceptual understanding, 2) self-efficacy, 3) intention to persist, and 4) feelings of inclusion

Results

Table 2: Mean (standard deviation) of scores on the 29-item DCI at the beginning of the semester (pre), end of the semester (post), and overall gain (defined in [4] as (post-pre)/(100%-pre)).

	pre %	post %	gain
Control	37.7 (14.6)	46.1 (18.3)	0.14 (0.22)
Intervention	40.6 (14.9)	46.9 (17.2)	0.10 (0.23)

Table 3: Results for t-tests conducted on gains and means (standard deviations) of gains for LAESE subfactors (engineering self-efficacy (ESE), inclusion (INC), persistence (PER), course-specific self-efficacy (CSE)).

	ESE		INC		PER		CSE	
	gain	p	gain	p	gain	p	gain	p
Control	-0.01 (0.12)	0.34	0.03 (0.13)	<0.01*	-0.01 (0.09)	0.75	-0.05 (0.25)	0.01*
Intervention	-0.01 (0.10)	0.08	-0.02 (0.14)	0.03*	0.02 (0.07)	<0.001*	-0.03 (0.21)	0.01*

*Significant at $\alpha = 0.05$.

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Methods

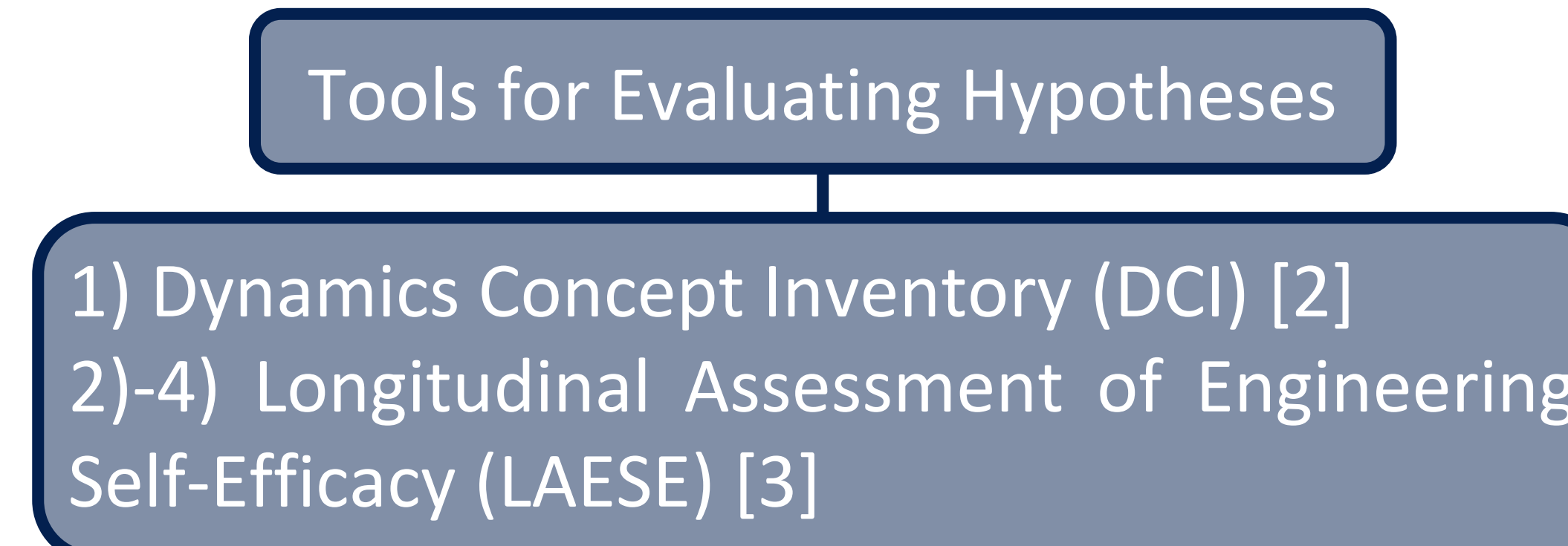


Figure 1: An iNewton with the sensor-fixed frame of reference etched on top. It contains a triaxial accelerometer and angular rate gyro, which measure linear acceleration and angular velocity, respectively.

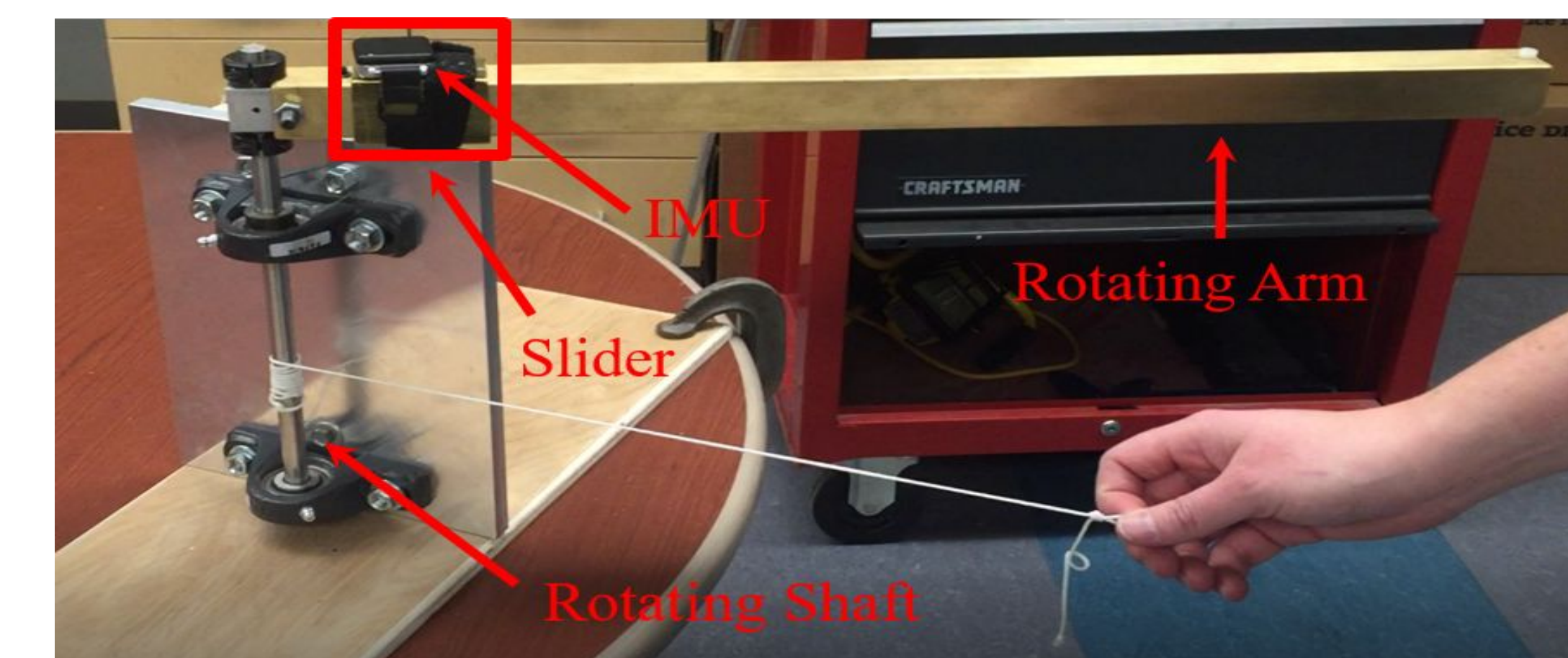
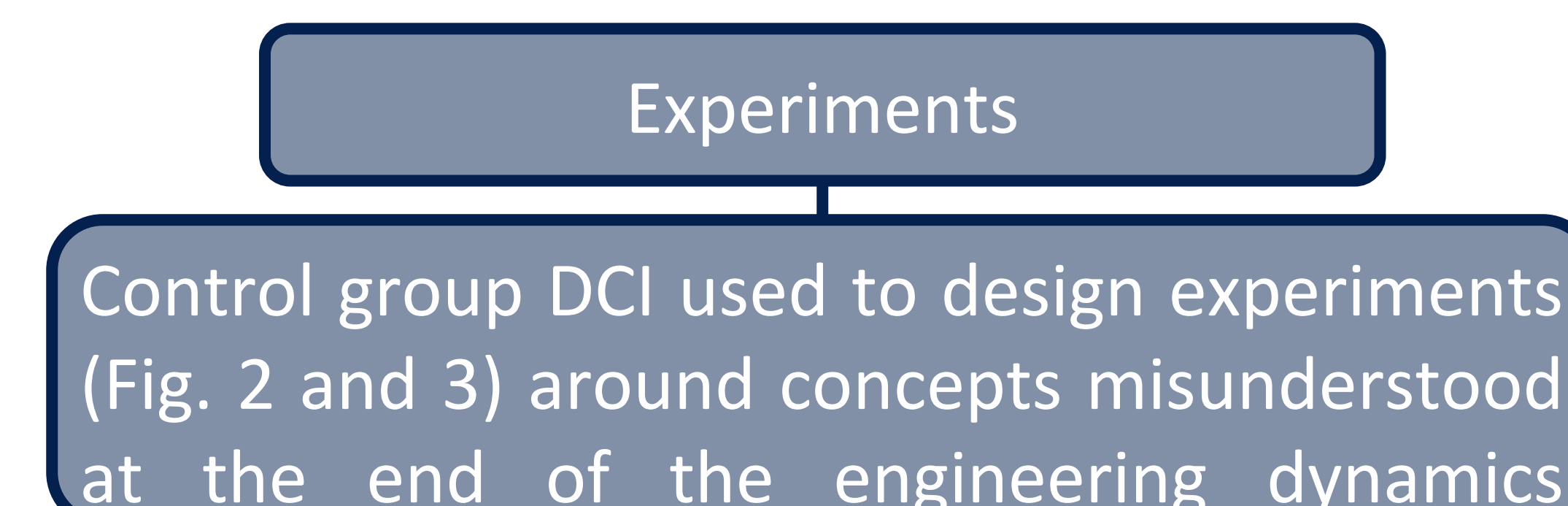


Figure 2: Experiment 1 set-up of a rotating arm with a slider that demonstrates the Coriolis acceleration.

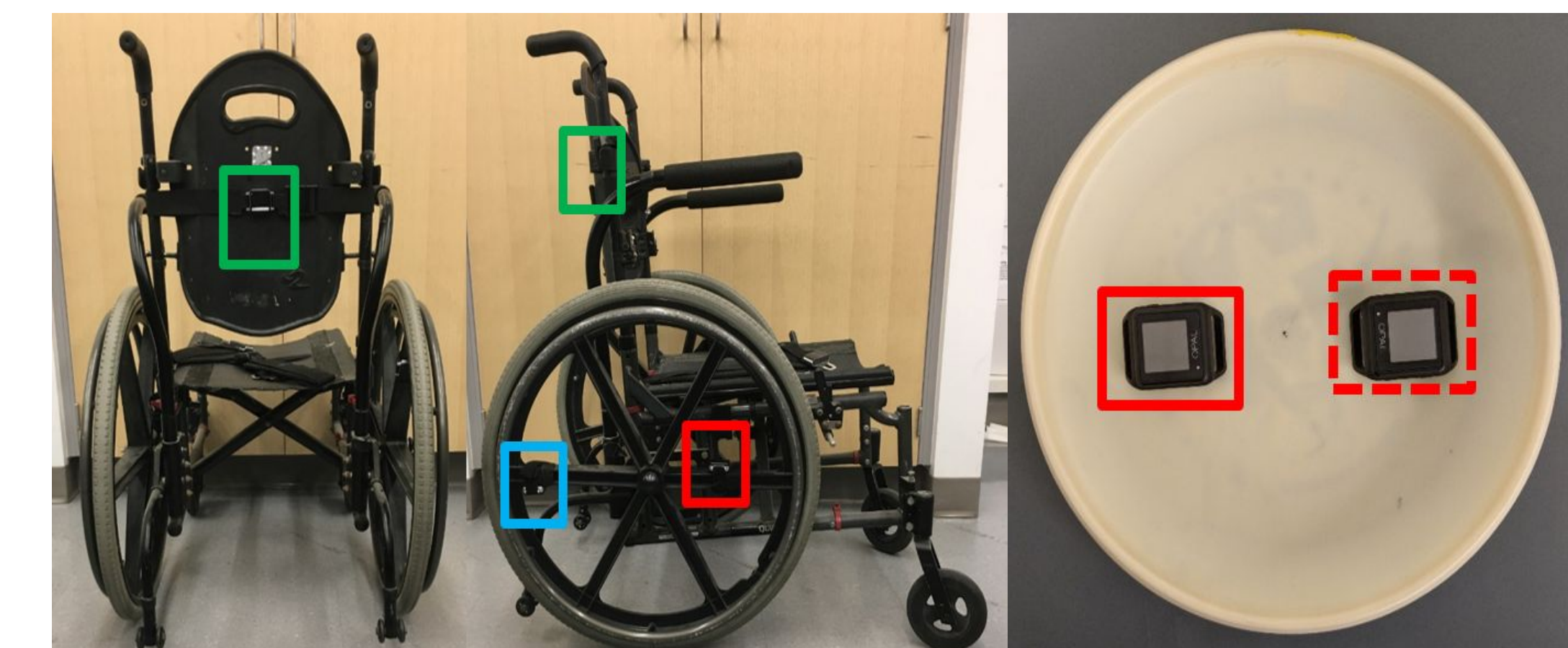
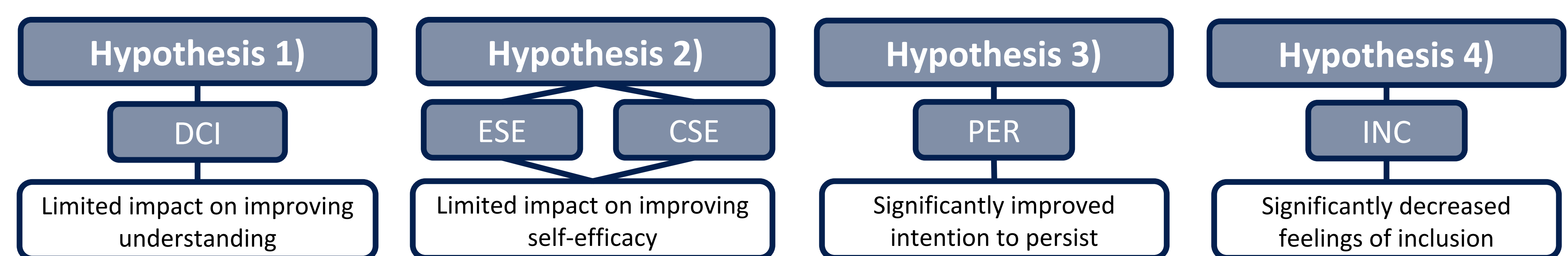


Figure 3: The two versions of experiment 2. (a) The wheelchair version included three IMUs located on the back of the chair (green), on a wheel near the outer perimeter (blue), and on the same wheel near the axle (red). (b) The Frisbee version included two IMUs located radially-symmetric on the underside. The IMU in the solid red box collected data for the assignment whereas the IMU in the dashed red box was added to minimize eccentric mass effects.

Conclusions and Future Work



First level of intervention not enough to improve significantly over the control group. Next levels require more engagement with iNewton, which will hypothetically improve results.

References

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